

Extensions of the Heisenberg Group

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The Heisenberg Group

Definition

The Heisenberg Group, often denoted by H_1 , is the group of 3×3 matrices consisting of elements of the form

$$\begin{pmatrix} 1 & x & z \\ 0 & 1 & y \\ 0 & 0 & 1 \end{pmatrix}$$

in \mathbb{R}^3 which we will denote (x, y, z) . Thus, the identity element e is $(0, 0, 0)$.

Then we can define

$$(x, y, z) \cdot (x', y', z') = \begin{pmatrix} 1 & x & z \\ 0 & 1 & y \\ 0 & 0 & 1 \end{pmatrix} \cdot \begin{pmatrix} 1 & x' & z' \\ 0 & 1 & y' \\ 0 & 0 & 1 \end{pmatrix} = \begin{pmatrix} 1 & x + x' & z + z' + xy' \\ 0 & 1 & y + y' \\ 0 & 0 & 1 \end{pmatrix}$$

which is written $(x + x', y + y', z + z' + xy')$.

The Heisenberg Group can also be thought of in higher dimensions. The Heisenberg group of $2n + 1$ dimensions in \mathbb{R}^{2n+1} is usually denoted H_n and is the group of matrices under matrix multiplication consisting of elements of the form

$$\begin{pmatrix} 1 & x & z \\ 0 & I_n & y \\ 0 & 0 & 1 \end{pmatrix},$$

with x a row vector of length n , y a column vector of length n , and I_n the identity matrix of n dimensions.

Example

Let $n, m, x, y, z \in \mathbb{R}$. H_2 , the 5-dimensional Heisenberg group is the group of matrices with elements of the form

$$\begin{pmatrix} 1 & x_1 & x_2 & z \\ 0 & 1 & 0 & y_1 \\ 0 & 0 & 1 & y_2 \\ 0 & 0 & 0 & 1 \end{pmatrix},$$

we will denote this element (x_1, x_2, y_1, y_2, z) . Then the identity element of H_2 is $(0, 0, 0, 0, 0)$ and

$$(x_1, x_2, y_1, y_2, z)^{-1} = (-x_1, -x_2, -y_1, -y_2, x_1y_1 + x_2y_2 - z).$$

Example

As for group multiplication we have

$$\begin{aligned} & (x_1, x_2, y_1, y_2, z)(x'_1, x'_2, y'_1, y'_2, z') \\ &= \begin{pmatrix} 1 & x_1 & x_2 & z \\ 0 & 1 & 0 & y_1 \\ 0 & 0 & 1 & y_2 \\ 0 & 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & x'_1 & x'_2 & z' \\ 0 & 1 & 0 & y'_1 \\ 0 & 0 & 1 & y'_2 \\ 0 & 0 & 0 & 1 \end{pmatrix} \\ &= \begin{pmatrix} 1 & x_1 + x'_1 & x_2 + x'_2 & z + z' + x_1x_2 + y_1y_2 \\ 0 & 1 & 0 & y_1 + y'_1 \\ 0 & 0 & 1 & y_2 + y'_2 \\ 0 & 0 & 0 & 1 \end{pmatrix} \\ &= (x_1 + x'_1, x_2 + x'_2, y_1 + y'_1, y_2 + y'_2, z + z' + x_1y'_1 + x_2y'_2). \end{aligned}$$

Group Extensions

Definition

An extension of a group H by a group N is a group G with a normal subgroup M such that $M \cong N$ and $G/M \cong H$. This information can be encoded into a short exact sequence of groups

$$1 \rightarrow N \rightarrow G \rightarrow H \rightarrow 1,$$

where $\alpha : N \rightarrow G$ is injective and $\beta : G \rightarrow H$ is surjective. Also, the image of α is the kernel of β .

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where $\alpha : N \rightarrow G$ is injective and $\beta : G \rightarrow H$ is surjective. Also, the image of α is the kernel of β .

In other words, if G is an extension of H by N then N is a normal subgroup of G and the quotient group G/N is isomorphic to group H .

Definition

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Example

Consider a group N consisting of elements of the form

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Example

Then N is a subgroup of the Heisenberg group H_1 since

$$\begin{pmatrix} 1 & 0 & z \\ 0 & 1 & y \\ 0 & 0 & 1 \end{pmatrix}^{-1} = \begin{pmatrix} 1 & 0 & -z \\ 0 & 1 & -y \\ 0 & 0 & 1 \end{pmatrix}$$

which is clearly in N and

$$\begin{pmatrix} 1 & 0 & z \\ 0 & 1 & y \\ 0 & 0 & 1 \end{pmatrix} \cdot \begin{pmatrix} 1 & 0 & z' \\ 0 & 1 & y' \\ 0 & 0 & 1 \end{pmatrix} = \begin{pmatrix} 1 & 0 & z + z' \\ 0 & 1 & y + y' \\ 0 & 0 & 1 \end{pmatrix}$$

which is also in N .

Example

Furthermore, N is a normal subgroup of H_1 because

$$\begin{aligned} &= \begin{pmatrix} 1 & a & c \\ 0 & 1 & b \\ 0 & 0 & 1 \end{pmatrix} \cdot \begin{pmatrix} 1 & 0 & z \\ 0 & 1 & y \\ 0 & 0 & 1 \end{pmatrix} \cdot \begin{pmatrix} 1 & a & c \\ 0 & 1 & b \\ 0 & 0 & 1 \end{pmatrix}^{-1} \\ &= \begin{pmatrix} 1 & a & c \\ 0 & 1 & b \\ 0 & 0 & 1 \end{pmatrix} \cdot \begin{pmatrix} 1 & 0 & z \\ 0 & 1 & y \\ 0 & 0 & 1 \end{pmatrix} \cdot \begin{pmatrix} 1 & -a & ab - c \\ 0 & 1 & -b \\ 0 & 0 & 1 \end{pmatrix} \\ &= \begin{pmatrix} 1 & 0 & z - ay \\ 0 & 1 & y \\ 0 & 0 & 1 \end{pmatrix} \in N. \end{aligned}$$

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Since $H_1/N \cong \{(x, 0, 0) \in H_1\}$, we can construct an exact sequence of groups.

$$e \rightarrow N \rightarrow H_1 \rightarrow \{(x, 0, 0)\} \rightarrow e$$

Example

Now consider a group A in \mathbb{R}^4 with elements of the form (x, y, z, d) . The group multiplication is defined by

$$(x, y, z, d) \cdot (x', y', z', d') = (e^{d'}x + x', e^{-d'}y + y', z + z' + e^{d'}(x \cdot y'), d + d').$$

Let $(x, y, z, 0) \in H_1$. Then H_1 is a subgroup of A because

$$(x, y, z, 0)^{-1} = (-x, -y, xy - z, 0) \in A \text{ and}$$

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Then it is simple to show that the Heisenberg group H_1 is a normal subgroup of A and that $A/G = \{(0, 0, 0, d) \in A\}$. Therefore, we have the following exact sequence

$$e \rightarrow H_1 \rightarrow A \rightarrow \{(0, 0, 0, d)\} \rightarrow e.$$

Cocycles

Definition

Let N be an abelian group. Given a group H , a 2-cocycle of H having values in N is a mapping ω from $H \times H$ to N satisfying the following cocycle identity

$$\omega(r, s)\omega(rs, t) = \omega(s, t)\omega(r, st) \forall r, s, t \in H.$$

Often, it is further assumed that $\omega(1, s) = \omega(s, 1) = 1$ for all $s \in H$.

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Proposition

If we have a suitable 2-cocycle $\omega : H \times H \rightarrow N$, then we can use it to define a group $N \times H$ with group multiplication defined by

$$(m, s) \times_{\omega} (n, t) = (mn\omega(s, t), st).$$

Definition

A bilinear form is a map $B : V \times V \rightarrow F$ where V is a vector space and F a field with the following properties for all $u, v \in V$ and λ fixed in F .

- 1 $B(u + u', v) = B(u, v) + B(u', v)$
- 2 $B(u, v + v') = B(u, v) + B(u, v')$
- 3 $B(\lambda u, v) = B(u, \lambda v) = \lambda B(u, v)$

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Definition

For finite dimensions, a bilinear form is nondegenerate if and only if $B(u, v) = 0$ for all $v \in V$ implies that $u = 0$.

Proposition

If α is a nondegenerate alternating \mathbb{R} -bilinear form $\mathbb{R}^{2n} \times \mathbb{R}^{2n} \rightarrow \mathbb{R}$ then the $(2n + 1)$ -dimensional Heisenberg group H_n^α fits into an exact sequence

$$e \rightarrow \mathbb{R} \rightarrow H_n^\alpha \rightarrow \mathbb{R}^{2n} \rightarrow e$$

and is the set of pairs $(t, v) \in \mathbb{R} \times \mathbb{R}^{2n}$, with the group operation defined as

$$(t_1, v_1)(t_2, v_2) = (t_1 + t_2 + \alpha(v_1, v_2), v_1 + v_2).$$

Example

Let $z \in \mathbb{R}$ and $v \in \mathbb{R}^2$ with $\alpha_1(v, v') = \alpha_1((x, y), (n, m)) = xm - yn$. α_1 is an alternating nondegenerate bilinear form.

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Therefore, by the last proposition, we have a group multiplication on \mathbb{R}^3 with identity element $(0, 0, 0)$ and $(x, y, z)^{-1} = (-x, -y, -z)$ with our group operation defined by

$$\begin{aligned} & (z_1, v_1)(z_2, v_2) \\ &= (z_1, (x_1, y_1))(z_2, (x_2, y_2)) \\ &= (z_1 + z_2 + \alpha_2((x_1, y_1), (x_2, y_2)), (x_1, y_1) + (x_2, y_2)) \\ &= (z_1 + z_2 + x_1y_2 - x_2y_1, (x_1 + x_2, y_1 + y_2)). \end{aligned}$$

In fact, this group is isomorphic to H_1 .

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Proof. Let $(z, x, y), (z', x', y') \in G$. Define a map $\phi : G \rightarrow H_1$ with $\phi((z, x, y)) = (z + xy, \sqrt{2}x, \sqrt{2}y)$. Then ϕ is a homomorphism because

$$\begin{aligned} & \phi((z, x, y)(z', x', y')) \\ &= \phi(z + z' + xy' - yx', x + x', y + y') \\ &= (z + z' + xy' - yx' + xy + x'y + xy' + x'y', \sqrt{2}(x + x'), \sqrt{2}(y + y')) \\ &= (z + xy + z' + x'y' + 2xy', \sqrt{2}(x + x'), \sqrt{2}(y + y')) \\ &= (z + xy, \sqrt{2}x, \sqrt{2}y)(z' + x'y', \sqrt{2}x', \sqrt{2}y') \\ &= \phi((z, x, y))\phi((z', x', y')). \end{aligned}$$

Furthermore, ϕ is one-to-one because if we set $\phi(z, x, y) = \phi(c, a, b)$ then we have $(z + xy, \sqrt{2}x, \sqrt{2}y) = (c + ab, \sqrt{2}a, \sqrt{2}b)$, which implies that $(z, x, y) = (c, a, b)$. ϕ is also onto since for every $(z, x, y) \in H_1$ there is an $(z - \frac{xy}{2}, \frac{1}{\sqrt{2}}x, \frac{1}{\sqrt{2}}y) \in G$ such that $\phi(z - \frac{xy}{2}, \frac{1}{\sqrt{2}}x, \frac{1}{\sqrt{2}}y) = (z, x, y)$.

Therefore, ϕ is an isomorphism as we wished to show. ■

Example

Let $z \in \mathbb{R}$ and $v \in \mathbb{R}^2$ with $\alpha_2(v_1, v_2) = \alpha_2((a, b), (a', b')) = a \cdot b'$. Then we have a group call it D with identity element $(0, 0, 0)$ and $(x, y, z)^{-1} = (-x, -y, xy - z)$ with group multiplication defined by

$$\begin{aligned}(c, v_1)(c', v_2) &= (c, (a, b))(c', (a', b')) \\ &= (c + c' + \alpha_2((a, b), (a', b')), (a, b) + (a', b')) \\ &= (c + c' + a \cdot b', (a + a', b + b')).\end{aligned}$$

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$$\begin{aligned}(c, v_1)(c', v_2) &= (c, (a, b))(c', (a', b')) \\ &= (c + c' + \alpha_2((a, b), (a', b')), (a, b) + (a', b')) \\ &= (c + c' + a \cdot b', (a + a', b + b')).\end{aligned}$$

This group operation is the same as the matrix multiplication of matrices in the Heisenberg group, so D and the Heisenberg group are isomorphic.

Theorem 6.7 of A.M. DuPre's paper "Real Heisenberg Group Extension Isomorphism Classes" states the following.

Theorem

Every 2-cocycle on the Heisenberg Group H_1 can be written in the form

$$\lambda_1(x^2y' + 2xz') + \lambda_2(y^2x' - x(y')^2 + 4yx'y' - 2xyy' - 6yz')$$

for fixed $\lambda_1, \lambda_2 \in \mathbb{R}$.

Example

Let N an abelian group. Using the equation in Theorem 2.9, set $\lambda_1 = 2$ and $\lambda_2 = 3$. Then define the map $\beta : H_1 \times H_1 \rightarrow N$ with

$$\beta((x, y, z)(x', y', z')) = 2(x^2y' + 2xz') + 3(y^2x' - x(y')^2 + 4yx'y' - 2xyy' - 6yz').$$

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Since it can be shown that β is a 2-cocycle satisfying the cocycle identity, Proposition 2.2 gives that there is a group operation on $H_1 \times N$. Let $x, y, z, d \in H_1 \times N$. Then $H_1 \times N$ has group operation defined by

$$\begin{aligned} & (x, y, z, d)(x', y', z', d') \\ &= (x + x', y + y', z + z' + xy', d + d' + \beta((x, y, z)(x', y', z'))) \\ &= (x + x', y + y', z + z' + xy', \\ & d + d' + 2(x^2y' + 2xz') + 3(y^2x' - x(y')^2 + 4yx'y' - 2xyy' - 6yz')), \end{aligned}$$

with identity element $(0, 0, 0, 0)$ and

$$(x, y, z, d)^{-1} = (-x, -y, -z + xy, -d - 2(x^2y - 2xz + 9yz - 3xy^2)).$$

The following theorem is arguably DuPre's most important result.

Theorem

Any two non-trivial, one-dimensional central extensions of the Heisenberg H_1 group yield isomorphic groups.